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**INFORMATION DISCLOSURE  
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Application Number

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First Named Inventor

Takashi YAMAMOTO et al.

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**U.S. PATENTS AND PUBLISHED U.S. PATENT APPLICATIONS**

Examiner Initials	Cite No. <sup>1</sup>	Document Number	Issue or Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
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**Note: Submission of copies of U.S. Patents and published U.S. Patent Applications is not required.****FOREIGN PATENT DOCUMENTS**

Examiner Initials	Cite No. <sup>1</sup>	Foreign Patent Document	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear	Translation <sup>6</sup>
		Country Code <sup>3</sup> Number <sup>4</sup> Kind Code <sup>5</sup> (if known)				

**NON PATENT LITERATURE DOCUMENTS**

Examiner Initials	Cite No. <sup>1</sup>	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	Translation <sup>6</sup>
		Japanese Office Action dated August 7, 2007	No
		K. Nagasaka et al., "Stabilization of Dynamic Walk on a Humanoid Using Torso Position Compliance Control," 17 <sup>th</sup> Conference of Robotics Soc. Jap., Japan Robotics Society, Sept. 9, 1999, pp. 1193-94	Abstract
		K. Satoshi, "Design and Implementation of Remotely Operation Interface for Humanoid Robot," Proc. 2001 IEEE Intl. Conf., Conference on Robotics & Automation, Seoul Korea, May 21-26-2001, pp. 401-406	Yes

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Considered

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